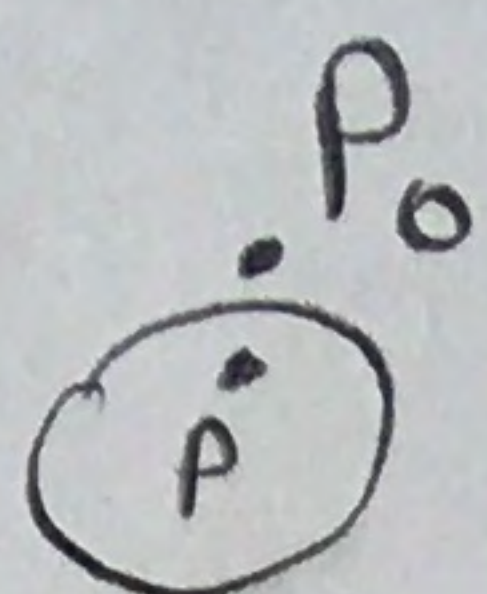
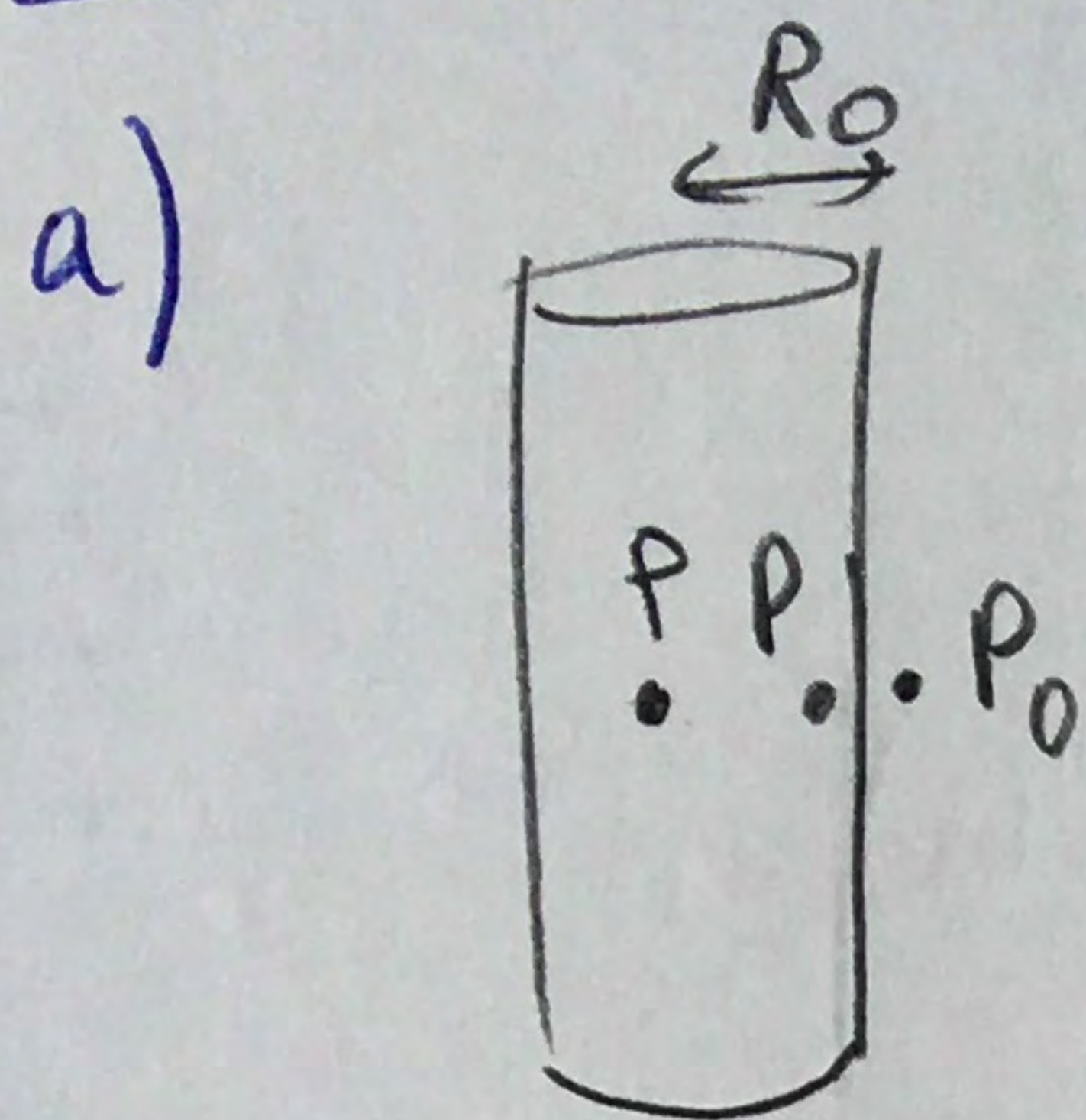


TD3 ex 4 (1)



loi de Laplace :

$$\underbrace{\Delta P}_{>0} = \underbrace{\frac{\gamma}{R_0}}_{>0} = \underbrace{P - P_0}_{>0}$$

car "P pousse l'interface"

$$\Rightarrow P = P_0 + \frac{\gamma}{R_0} \text{ vrai } \forall z$$

$\Rightarrow \forall z$, proche de l'interface,

$$P = P_0 + \frac{\gamma}{R_0}$$

pression dans le reste du cylindre ?

$$\text{hydrostatique} \Rightarrow P_A - P_B = -\rho g (z_A - z_B) = 0 \Rightarrow P_A = P_B$$

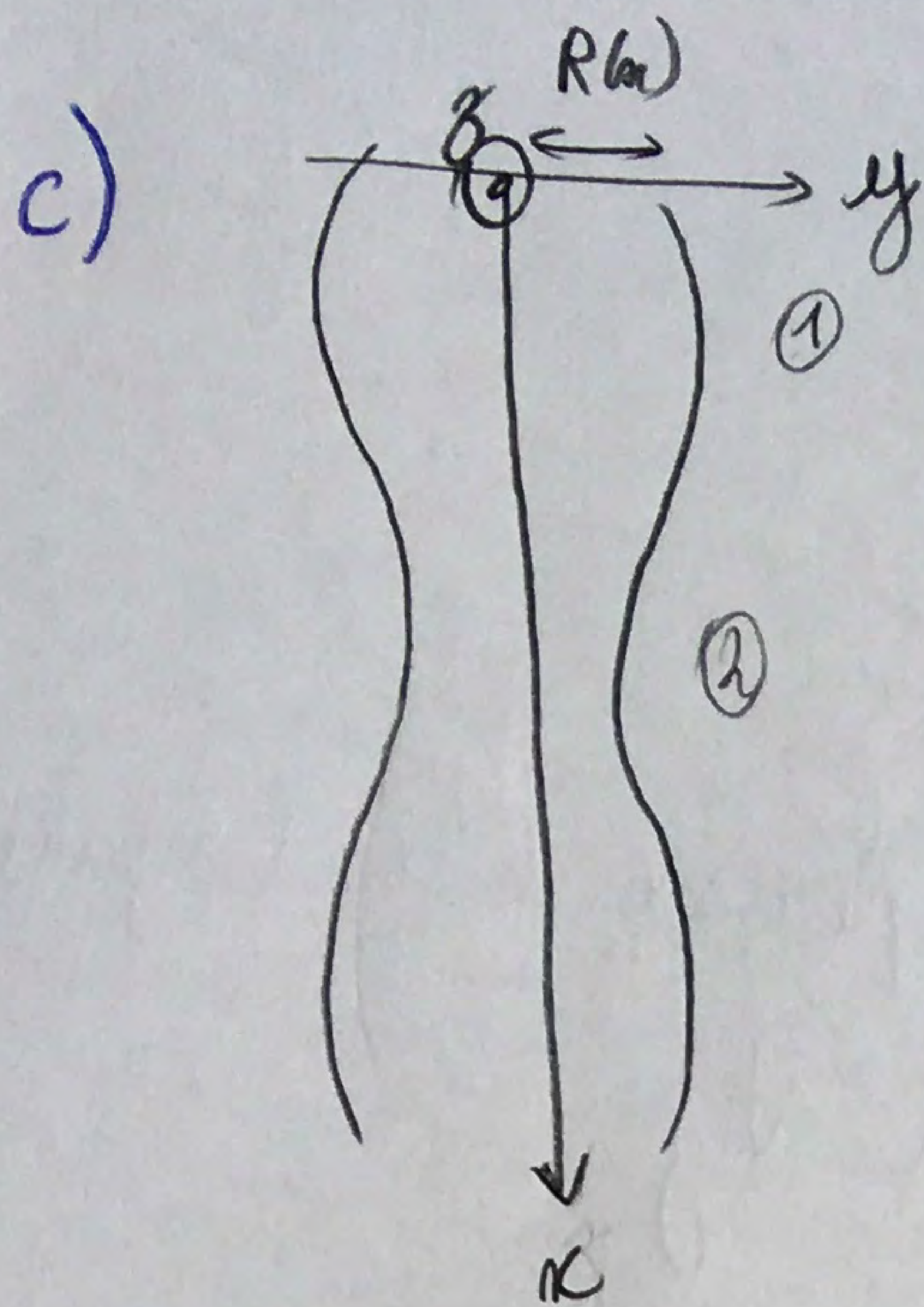
$= 0 \text{ si } z_A = z_B$

$\text{si } z_A = z_B$

à z donné, $P = \text{cte}$ dans tout le cercle.

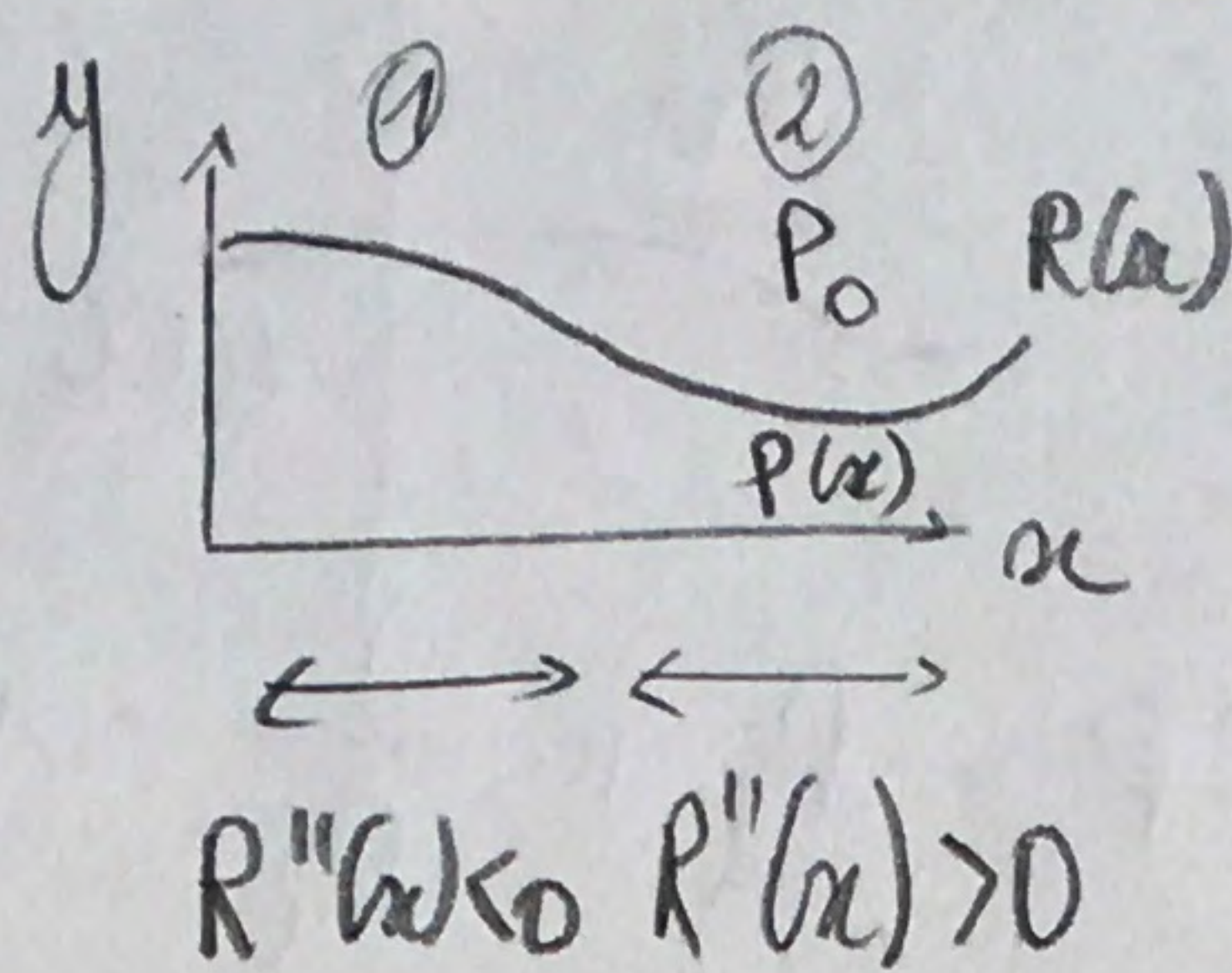
conclusion

dans tout le cylindre $P = P_0 + \frac{\gamma}{R_0}$



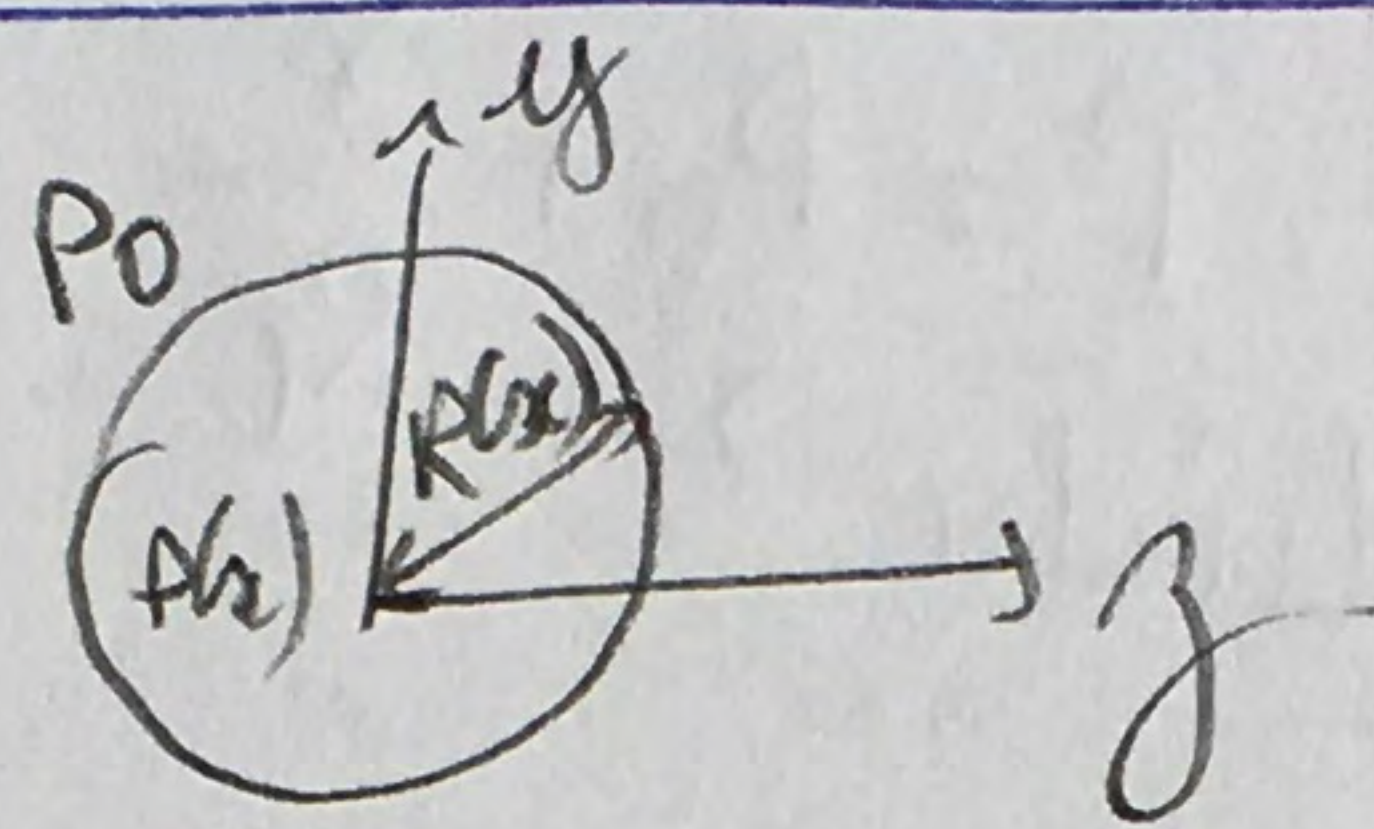
$$R(x) = R_m + \varepsilon \cos(kx)$$

dans le plan (x, y) :



$$(p_0 - p)_{xy} = \gamma R''(x)$$

dans le plan (y, z) :



$$(p(x) - p_0)_{yz} = \frac{\gamma}{R(x)}$$

d'où: $p(x) - p_0 = \frac{\gamma}{R(x)} - \gamma R''(x)$

$$= \frac{\gamma}{R_m + \varepsilon \cos(kx)} + \gamma \varepsilon k^2 \cos(kx)$$

$$\approx \frac{\gamma}{R_m} \left(1 - \frac{\varepsilon}{R_m} \cos(kx) \right)$$

$\frac{1}{1+\alpha} \sim 1-\alpha$

$$p(x) - p_0 = \gamma \varepsilon \cos(kx) \left(k^2 - \frac{1}{R_m^2} \right)$$

① $R''(x) < 0$
 $\cos(kx) > 0$
② $R''(x) > 0$
 $\cos(kx) < 0$

< 0

$$\begin{pmatrix} p_- \\ \uparrow \\ p_+ \\ \downarrow \\ p_- \end{pmatrix}$$

si $k^2 R_m^2 < 1$, | en ① $p(x) - p_0 < 0 \Rightarrow p^-$ (dépress°)
| en ② $p(x) - p_0 > 0 \Rightarrow p^+$ (surpress°)

écoulement va des hautes pressions vers les basses (surpress° pousse, dépress° aspire).
 $\Rightarrow$ écoulement depuis les creux vers les bosses $\Rightarrow$ l'amplitude de la perturbation augmente $\Rightarrow$ instabilité

TD3 ex 4 (2)

d) conservation de la masse entre filet non perturbé et filet perturbé.

($\rho = \text{cte} \Rightarrow$ conservation du volume) $\Rightarrow V_i = V_p$.

• filet non perturbé :

$$V_i = \pi R_0^2 \lambda$$

• filet perturbé :

$$V_p = \int_{x=0}^{\lambda} \int_{\theta=0}^{2\pi} \int_{r=0}^{R(x)} r d\theta dr dx$$

$$= 2\pi \int_{x=0}^{\lambda} \frac{R^2(x)}{2} dx$$

$$= \pi \int_{x=0}^{\lambda} (R_m + \varepsilon \cos(kx))^2 dx$$

$$= \pi R_m^2 \int_{x=0}^{\lambda} \left(1 + \frac{2\varepsilon}{R_m} \cos(kx) + \frac{\varepsilon^2}{R_m^2} \cos^2(kx) \right) dx$$

$$\frac{1 + \cos(2kx)}{2}$$

$$= \pi R_m^2 \left(\lambda + \frac{2\varepsilon}{R_m k} \underbrace{\sin(k\lambda)}_{=0 \text{ car } k\lambda=2\pi} + \frac{\varepsilon^2}{2R_m^2} \lambda + \frac{\varepsilon^2}{4R_m^2 k} \underbrace{\sin(2k\lambda)}_{=0} \right)$$

$$V_p = \pi \lambda R_m^2 \left(1 + \frac{\varepsilon^2}{2} \right)$$

$$V_i = V_p \Rightarrow \cancel{\pi R_0^2} \cancel{\lambda} = \cancel{\pi} \cancel{\lambda} \left(R_m^2 + \frac{\epsilon^2}{2} \right)$$

$$\Rightarrow R_m = \sqrt{R_0^2 - \frac{\epsilon^2}{2}}$$

$$= R_0 \sqrt{1 - \frac{\epsilon^2}{2R_0^2}}$$

$$\boxed{R_m \approx R_0 \left(1 - \frac{\epsilon^2}{4R_0^2} \right)}$$

e) TD 3 ex 4 (3)
surface initiale : $S_i = 2\pi R_0 \lambda$

surface perturbée :

$$S_p = \int_{\theta=0}^{2\pi} \int_{l=0}^{l(\lambda)} R(x) d\theta dl$$

$$= 2\pi \int_{n=0}^{\lambda} R_m \left(1 + \frac{\varepsilon \cos(kx)}{R_m} \right) \left(1 + \frac{1}{2} \varepsilon^2 k^2 \sin^2(kx) \right) dx$$

$$= 2\pi R_m \int_{n=0}^{\lambda} \left(1 + \frac{\varepsilon \cos(kx)}{R_m} + \frac{1}{2} \varepsilon^2 k^2 \frac{\sin^2(kx)}{1 - \cos(2kx)} + O(3) \right) dx$$

$$= 2\pi R_m \left(\lambda + \frac{\varepsilon}{R_m k} \underbrace{\sin(k\lambda)}_{=0} + \frac{\varepsilon^2 k^2}{4} \lambda - \frac{\varepsilon^2 k^2}{4} \underbrace{\frac{\sin(2k\lambda)}{2k}}_{=0} \right)$$

$$= 2\pi R_m \lambda \left(1 + \frac{\varepsilon^2 k^2}{4} \right)$$

$$S_p = 2\pi R_m \lambda \left(1 + \frac{\varepsilon^2 \pi^2}{\lambda^2} \right)$$

$$S_p - S_0 = 2\pi R_m \lambda \left(1 + \frac{\varepsilon^2 \pi^2}{\lambda^2} \right) - 2\pi R_0 \lambda$$

$$= 2\pi \lambda \left(R_m - R_0 + \frac{\varepsilon^2 \pi^2}{\lambda^2} R_m \right)$$

$$= 2\pi \lambda R_0 \left(\cancel{1} - \frac{\varepsilon^2}{4R_0^2} - \cancel{1} + \frac{\varepsilon^2 \pi^2}{\lambda^2} \left(1 - \frac{\varepsilon^2}{4R_0^2} \right) \right)$$

$$= 2\pi \lambda R_0 \left(-\frac{\varepsilon^2}{4R_0^2} + \frac{\varepsilon^2 \pi^2}{\lambda^2} + O(4) \right)$$

calcul de dl
 $dl^2 = dx^2 + dR^2$
 $dl = dx \sqrt{1 + \left(\frac{dR}{dx} \right)^2}$
 $R'(x) = -\varepsilon k \sin(kx)$
 $\ll 1$ car $\varepsilon k \ll 1$
 $\sim dx \left(1 + \frac{1}{2} \left(\frac{dR}{dx} \right)^2 \right) \sim dx \left(1 + \frac{1}{2} (-\varepsilon k \sin(kx))^2 \right)$
 $dl \sim dx \left(1 + \frac{1}{2} \varepsilon^2 k^2 \sin^2(kx) \right)$

$$S_p - S_0 < 0 \Rightarrow \frac{\varepsilon^2 \pi^2}{\lambda^2} < \frac{\varepsilon^2}{4 R_0^2}$$

$$\Rightarrow \lambda^2 > 4 \pi^2 R_0^2$$

$$\Rightarrow \lambda > 2 \pi R_0$$

$$\Rightarrow \frac{\lambda}{2 R_0} > \pi \in [3, 13; 3, 18] \rightarrow \text{en accord avec Plateau}$$

Si $S_p - S_0 < 0$, $S_p < S_0$ donc pour minimiser l'énergie de surface, le système favorisera l'état perturbé.